

- Preliminary stuff:
- choose a problem from 2018 midterm to review
 - announcements about the exam.

	function $f(x,y,z)$	vector field $\vec{F}(x,y,z)$
curve $C \subset \mathbb{R}^3$	$\int_C f ds = \int_a^b f(\vec{r}(t)) \vec{r}'(t) dt$	$\int_C \vec{F} \cdot d\vec{r} = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$ $= \int_C \vec{F} \cdot \vec{T} ds$
surface $S \subset \mathbb{R}^3$	$\iint_S f dS = \iint_D f(\vec{r}(u,v)) \vec{r}_u \times \vec{r}_v dA$?? Today: find out!

- Remarks
- [see slides]
- doesn't depend on choice of parametrization
 - For curves we looked at the tangent vector (and its length).

For surfaces, there are infinitely many directions for tangent vectors

But there's a unique line of normal vectors, " $\vec{r}_u \times \vec{r}_v$ ".



- For curves, the choice of orientation tells us whether we take tangent vector pointing to the left or the right



For surfaces a choice of orientation will tell us whether to take the normal vector pointing up or down.



Definition: Let S be a surface in \mathbb{R}^3 .

S is orientable if it has two sides

- inside & outside / top & bottom.
- You can paint them two different colours.

Definition: S is oriented if we choose one of the sides. 38 | 34.2

→ then we always know to take the unit normal vector pointing out of the chosen side; we write \vec{n} .

① Take a strip of paper, and tape the ends together to form a cylinder. Is it orientable?

② Now tape the ends together with a half-twist. This is a Möbius strip. Is it orientable?

Let \vec{F} be the (continuous) velocity field of a fluid flow on \mathbb{R}^3 . Let S be an oriented surface, with \vec{n} the unit normal vector.

Definition: the flux of \vec{F} across S is

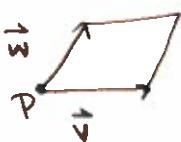
$$\iint_S \vec{F} \cdot d\vec{S} := \iint_S \vec{F} \cdot \vec{n} dS$$

Note: if $-S$ is S with the opposite orientation, then

$$\iint_{-S} \vec{F} \cdot d\vec{S} = - \iint_S \vec{F} \cdot d\vec{S}.$$

Claim: The flux is the (signed) volume of fluid flowing across S in unit time.

Why? Cover S with tiny patches S_{ij} and approximate each S_{ij} by parallelograms.



$$\text{with } \vec{n} = \frac{\vec{v} \times \vec{w}}{|\vec{v} \times \vec{w}|} \text{ over all of } S_{ij}$$

$$\vec{F} \approx \text{constant } \vec{F}(P) \text{ over } S_{ij}$$

⇒ flux across S_{ij} is $\frac{\vec{F} \cdot \vec{n}}{\text{component of } \vec{F} \text{ in the direction of } \vec{n}} \Delta A$.

Let S be a smooth oriented surface with unit normal vector \vec{n} .

Parametrize S by $\vec{r}(u, v)$, $(u, v) \in D \subset \mathbb{R}^2$.

$\vec{r}_u \times \vec{r}_v$ is perpendicular to S at each point.

Def. S is positively oriented if $\frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} = \vec{n}$ and negatively oriented if $\frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} = -\vec{n}$.

Theorem Let \vec{F} be a continuous vector field on S . [34.3]

If $\vec{r}_u \times \vec{r}_v$ is positively oriented, then

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_D \vec{F}(\vec{r}(u,v)) \cdot (\vec{r}_u \times \vec{r}_v) dA.$$

proof:
$$\begin{aligned} \iint_S \vec{F} \cdot d\vec{S} &= \iint_S \vec{F} \cdot \vec{n} dS = \iint_D \vec{F}(\vec{r}(u,v)) \cdot \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} |\vec{r}_u \times \vec{r}_v| dA \\ &= \iint_D \vec{F}(\vec{r}(u,v)) \cdot \vec{r}_u \times \vec{r}_v dA. \quad \square \end{aligned}$$

Example: Let S be $\{z = \sqrt{x^2 + y^2}, 1 \leq z \leq 3\}$, oriented downward, and let $\vec{F} = \langle x, y, z^2 \rangle$.

Step 1: parametrize S :



$$\vec{r}(u, \theta) = \langle u \cos \theta, u \sin \theta, u \rangle, \quad 0 \leq \theta \leq 2\pi, \quad 1 \leq u \leq 3.$$

Step 2: Find $\vec{r}_u \times \vec{r}_\theta$ & compare to \vec{n} .

$$\cdot \vec{r}_u = \langle \cos \theta, \sin \theta, 1 \rangle; \quad \vec{r}_\theta = \langle -u \sin \theta, u \cos \theta, 0 \rangle$$

$$\Rightarrow \vec{r}_u \times \vec{r}_\theta = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos \theta & \sin \theta & 1 \\ -u \sin \theta & u \cos \theta & 0 \end{vmatrix} = \langle -u \cos \theta, -u \sin \theta, u \rangle$$

↑
points upward, not
downward.

So $\vec{r}_u \times \vec{r}_\theta$ is negatively oriented

Step 3: Calculate $\iint_S \vec{F} \cdot d\vec{S}$:

$$\begin{aligned} \iint_S \vec{F} \cdot d\vec{S} &= - \iint_D \vec{F}(\vec{r}(u, \theta)) \cdot (\vec{r}_u \times \vec{r}_\theta) dA \\ &= - \int_0^{2\pi} \int_1^3 \langle u \cos \theta, u \sin \theta, u^2 \rangle \cdot \langle -u \cos \theta, -u \sin \theta, u \rangle \cancel{dud\theta} \\ &= - \int_0^{2\pi} \int_1^3 -u^2 + u^3 dud\theta \dots \end{aligned}$$

Example: Let S be the graph of a function $f: D \rightarrow \mathbb{R}$, oriented upward.

34.4

Let \vec{F} be a continuous vector field on S .

Find $\iint_S \vec{F}(x,y,z) \cdot d\vec{S}$.

Step 1: parametrize S :

$$\vec{r}(u,v) = \langle u, v, f(u,v) \rangle, \quad (u,v) \in D.$$

Step 2: Calculate $\vec{r}_u \times \vec{r}_v$ and compare to \vec{n} .

$$\vec{r}_u = \langle 1, 0, f_x \rangle, \quad \vec{r}_v = \langle 0, 1, f_y \rangle$$

$$\Rightarrow \vec{r}_u \times \vec{r}_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & f_x \\ 0 & 1 & f_y \end{vmatrix} = \langle -f_x, -f_y, 1 \rangle.$$

② Is this positively or negatively oriented?

Step 3: Calculate $\iint_S \vec{F} \cdot d\vec{S}$.